Lazy Multivariate Higher-Order Forward-Mode AD

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Forward-Mode AD

$$\mathcal{D}f c \stackrel{\triangle}{=} \left. \frac{\mathrm{d}f(x)}{\mathrm{d}x} \right|_{x=c}$$

Wengert (1964)



Higher-Order Forward-Mode AD

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$$[f(c), f'(c), f''(c), \dots, f^{(i)}(c), \dots]$$

Wengert (1964), Karczmarczuk (2001)



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$$\mathcal{D}^{[i_1, \dots, i_n]} f [c_1, \dots, c_n] \stackrel{\triangle}{=} \frac{\partial^{i_1 + \dots + i_n} f(x_1, \dots, x_n)}{\partial x_1^{i_1} \dots \partial x_n^{i_n}} \bigg|_{x_1 = c_1, \dots, x_n = c_n}$$

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Taylor expansion:

$$f(c+\varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \dots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \dots$$

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(Analogous to complex numbers a + bi represented as $\langle a, b \rangle$.)

$$(x_0 + x_1\varepsilon + \mathcal{O}(\varepsilon^2)) + (y_0 + y_1\varepsilon + \mathcal{O}(\varepsilon^2)) = (x_0 + y_0) + (x_1 + y_1)\varepsilon + \mathcal{O}(\varepsilon^2)$$

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$$(x_0 + x_1\varepsilon + \mathcal{O}(\varepsilon^2)) \times (y_0 + y_1\varepsilon + \mathcal{O}(\varepsilon^2))$$
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$$= (b (x_{0}, y_{0})) + (x_{1} \times (b^{(1,0)} (x_{0}, y_{0})) + y_{1} \times (b^{(0,1)} (x_{0}, y_{0}))\varepsilon + \mathcal{O}(\varepsilon^{2})$$

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Non-truncated is harder: Cannot ignore $\mathcal{O}(\varepsilon^2)$ s.



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Need mechanism to support arbitrary nesting of power series.

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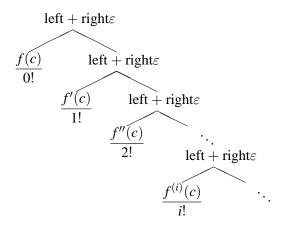
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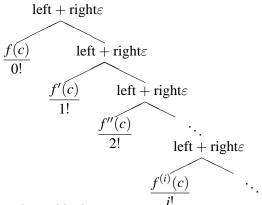
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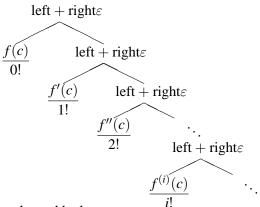
Bad news: The power series may be **infinite**.





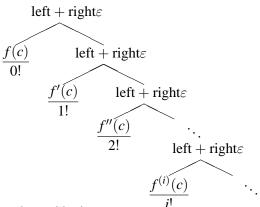


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API: $(\mathcal{Q} \varepsilon p)$ computes *quotient* of $\frac{p}{\varepsilon}$, analogous to forcing cdr. $(\mathcal{R} \varepsilon p)$ computes *remainder* of $\frac{p}{\varepsilon}$, analogous to car.

Multivariate Taylor expansion:

$$f((c_1 + \varepsilon_1), \dots, (c_n + \varepsilon_n)) = \sum_{i_1=0}^{\infty} \dots \sum_{i_n=0}^{\infty} \frac{1}{i_1! \cdots i_n!} \frac{\partial^{i_1 + \dots + i_n} f(x_1, \dots, x_n)}{\partial x_1^{i_1} \cdots \partial x_n^{i_n}} \bigg|_{\substack{\varepsilon_1^{i_1} \cdots \varepsilon_n^{i_n} \\ x_1 = \varepsilon_1, \dots, x_n = \varepsilon_n}}$$

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- multiply by $i_1! \cdots i_n!$.

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$$\sum_{i_1=0}^{\infty} \dots \sum_{i_n=0}^{\infty} \frac{1}{i_1! \dots i_n!} \frac{\partial^{i_1 + \dots + i_n} f(x_1, \dots, x_n)}{\partial x_1^{i_1} \dots \partial x_n^{i_n}} \Big|_{x_1 = c_1, \dots, x_n = c_n} \varepsilon_1^{i_1} \dots \varepsilon_n^{i_n}$$

To compute $\mathcal{D}^{[i_1,\ldots,i_n]}f[c_1,\ldots,c_n]$:

- evaluate f at $(c_1 + \varepsilon_1), \ldots, (c_n + \varepsilon_n)$ to get a **multivariate** power series,
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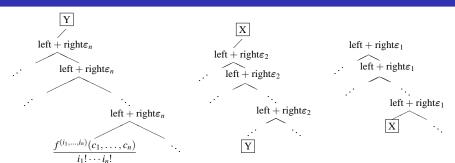
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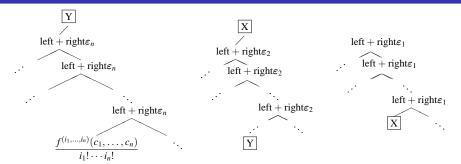
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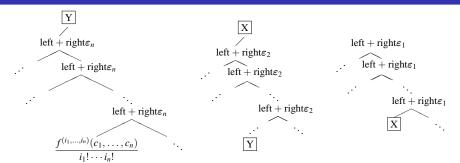
Bad news: Need a distinct ε_i for each argument of f (and for each nested invocation of \mathcal{D} , even in the univariate case).



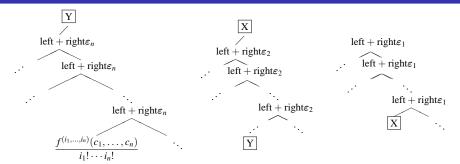




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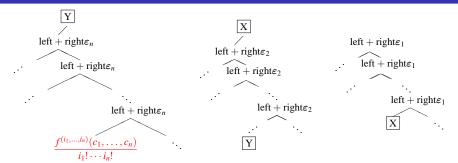
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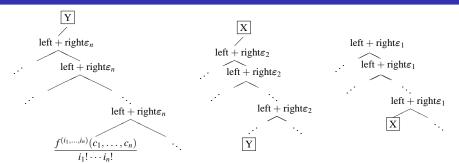


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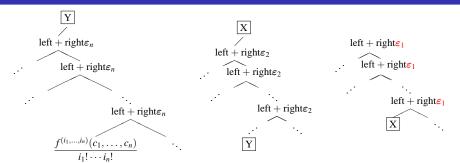


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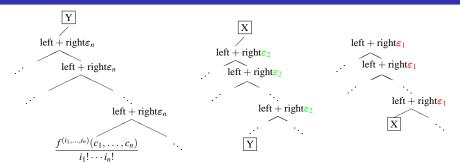


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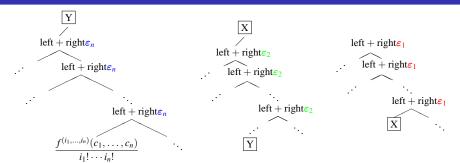


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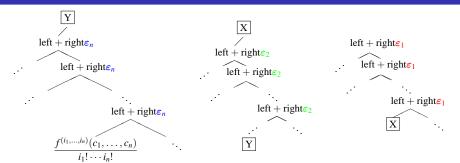


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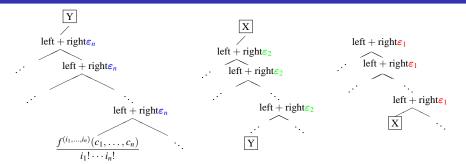
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Painfully ironic: Cannot *implement* \mathcal{D} in a referentially transparent language even though \mathcal{D} itself *is* referentially transparent!

$$u\left(x+x'\varepsilon\right)=(u\,x)+((\mathcal{C}_{\varepsilon^0}\,\left(u'\,\left(x+x'\varepsilon\right)[\varepsilon\mapsto\xi]\right))[\xi\mapsto\varepsilon]\times x')\varepsilon$$

• Unary primitives:

$$u(x+x'\varepsilon) = (ux) + ((\mathcal{C}_{\varepsilon^0}(u'(x+x'\varepsilon)[\varepsilon \mapsto \xi]))[\xi \mapsto \varepsilon] \times x')\varepsilon$$

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$$b\left((x+x'\varepsilon),(y+y'\varepsilon)\right) = (b\left((x+x'\varepsilon),(y+y'\varepsilon)[\varepsilon\mapsto\xi]\right))[\xi\mapsto\varepsilon]$$



Arithmetic on Non-Truncated Power Series

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• Read the paper for the details.



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- For functional programming to interest numerical computing, it should provide useful numeric constructs.
- For instance: exact efficient derivatives!
- We have shown how to implement an unrestricted multivariate higher-order derivative operator using forward-mode AD.

Contingency Slides

Forward AD of Non-Scalar Functions

Discussed scalar functions for expository simplicity

Can generalize higher-order scalar derivative

$$\mathcal{D}: \mathbb{N} \times (\mathbb{R} \to \mathbb{R}) \to (\mathbb{R} \to \mathbb{R})$$

to higher-order vector directional derivative

$$\mathcal{J}: \mathbb{N} \times (\mathbb{R}^n \to \mathbb{R}^m) \to (\mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^m)$$

• using same mechanisms: find directional *i*-th derivative \mathcal{J} if \mathbf{c} \mathbf{c}' of $f: \mathbb{R}^n \to \mathbb{R}^m$ at $\mathbf{c}: \mathbb{R}^n$ in direction $\mathbf{c}': \mathbb{R}^n$ by calculating

$$\mathbf{y} = f \left[c_1 + c_1' \varepsilon, \dots, c_n + c_n' \varepsilon \right]$$

and extracting

$$[y'_1,\ldots,y'_m]=[\mathcal{C}_{\varepsilon^i}\ y_1,\ldots,\mathcal{C}_{\varepsilon^i}\ y_m]$$



Representation and Factorials: A Technicality

Two alternatives for representing

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• Tower of Derivatives (with factorials)

$$\langle x(0), \langle x'(0), \langle x''(0), \langle x'''(0), \ldots \rangle \rangle \rangle \rangle$$

$$= \langle 0! \times x_0, \langle 1! \times x_1, \langle 2! \times x_2, \langle 3! \times x_3, \ldots \rangle \rangle \rangle \rangle$$

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- Identical in truncated case
- Fungible: trade off which "left shift" is fast,

$$Q \in x(\varepsilon) = \frac{1}{\varepsilon}(x(\varepsilon) - x(0))$$
 or $\frac{\mathrm{d}}{\mathrm{d}\varepsilon}x(\varepsilon)$

$$\mathcal{D}(\lambda x \ldots x \ldots) c$$

$$\mathcal{D}(\lambda y \ldots y \ldots) c$$

Observation I

$$\mathcal{D}(\lambda x \ldots x \ldots) c \qquad \mathcal{D}(\lambda y \ldots y \ldots) c$$

$$\mathcal{D} (\lambda x \dots (\mathcal{D} (\lambda y \dots x \dots y \dots) c) \dots) c$$

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